

NHD-0216K1Z-FSR-FBW-L

Character Liquid Crystal Display Module

NHD-	Newhaven Display
0216-	2 Lines x 16 Characters
K1Z-	Model
F-	Transflective
SR-	Side Red LED Backlight
F-	FSTN(+)
B-	6:00 Optimal View
W-	Wide Temperature
L-	Low Power 20mA
	RoHS Compliant

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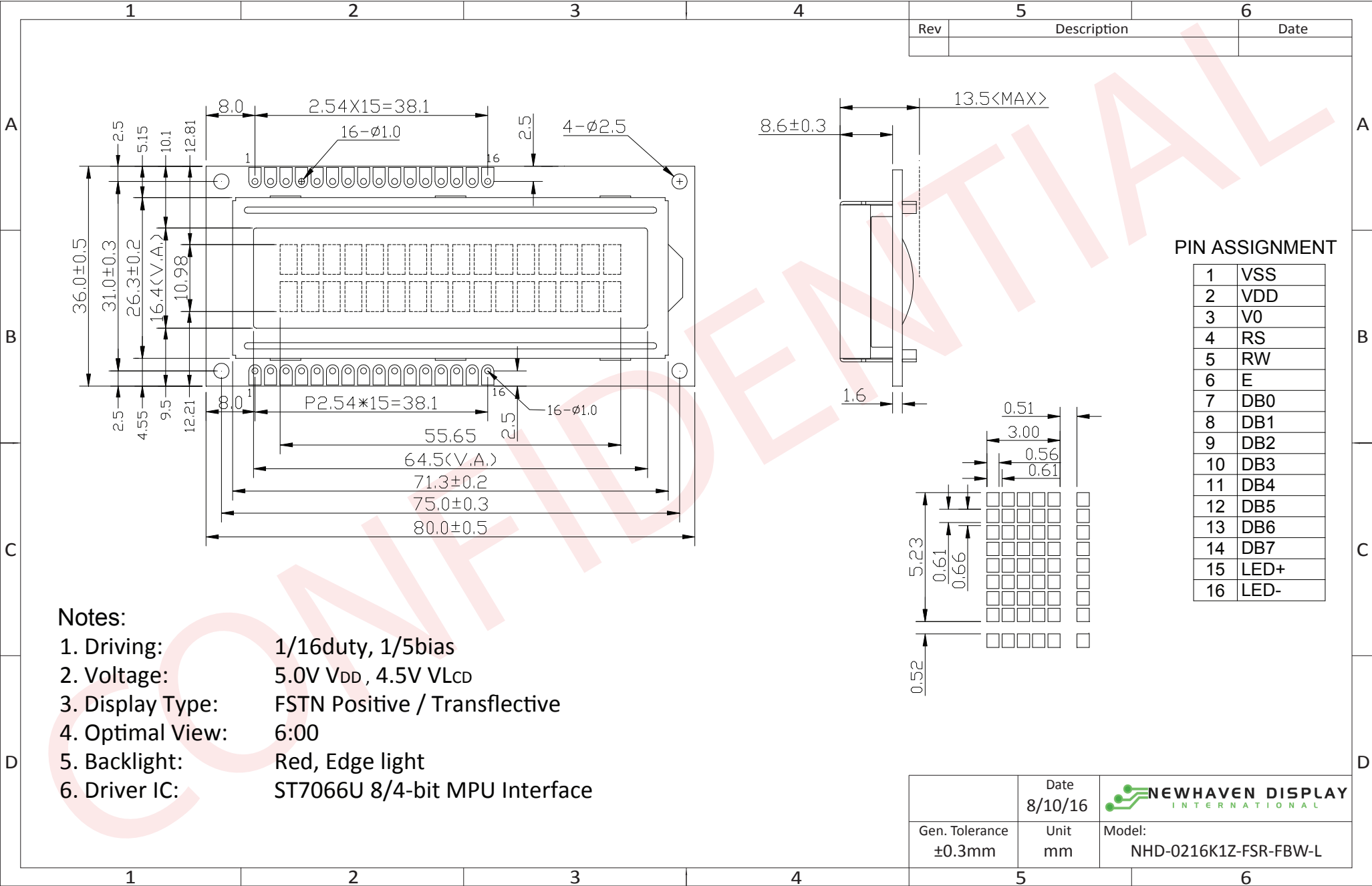
Document Revision History

Revision	Date	Description	Changed by
0	10/5/2007	Initial Release	-
1	12/16/2009	User Guide Reformat	BE
2	1/7/2010	Optical revised	BE
3	1/6/2011	Alternate controller information updated	AK
4	5/2/2011	Electrical characteristics updated	AK
5	12/18/2014	Mechanical drawing updated	AK
6	8/10/2016	Electrical characteristics, Mechanical drawing updated	TM

Functions and Features

- 2 lines x 16 characters
- Built-in controller (ST7066U)
- +5.0V Power Supply
- 1/16 duty, 1/5 bias
- RoHS compliant

Mechanical Drawing



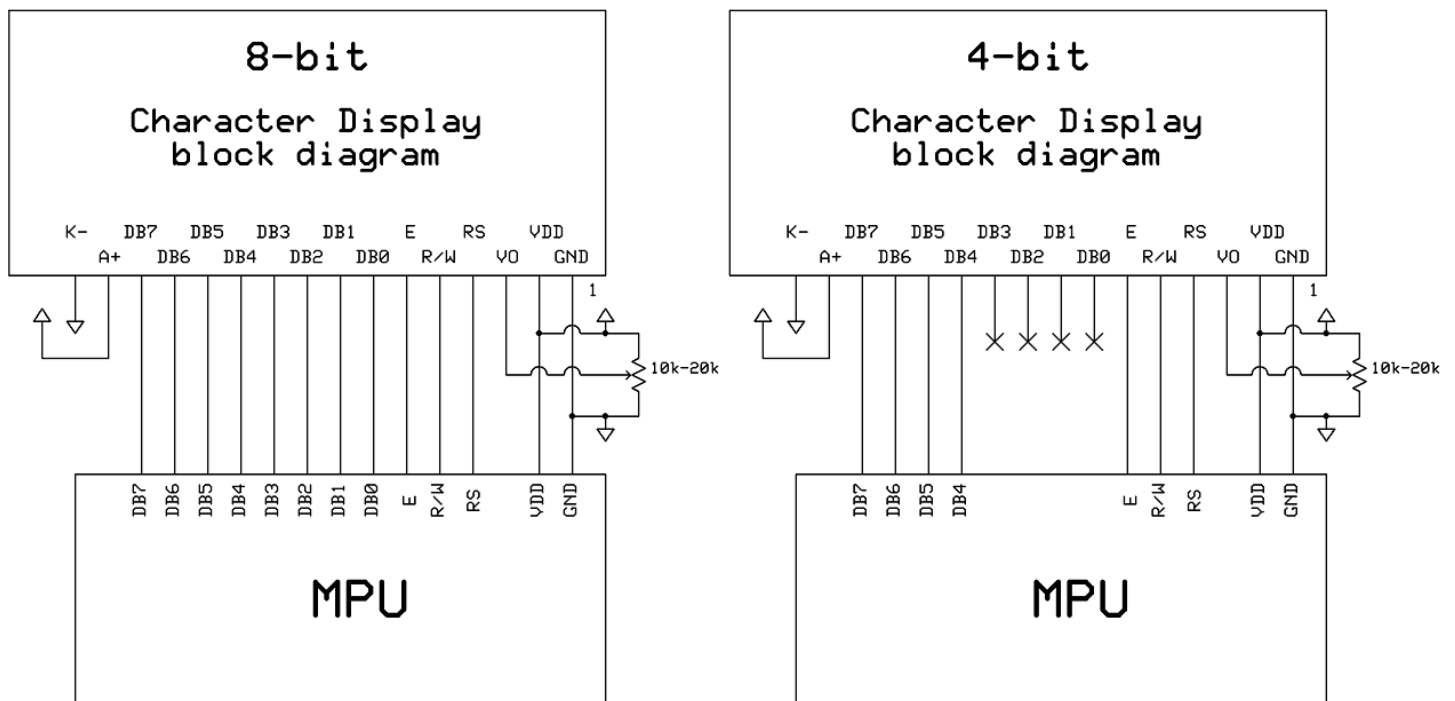
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Pin Description and Wiring Diagram

Pin No.	Symbol	External Connection	Function Description
1	V _{SS}	Power Supply	Ground
2	V _{DD}	Power Supply	Supply Voltage for logic (+5.0V)
3	V ₀	Adj Power Supply	Power supply for contrast (approx. 0.5V)
4	RS	MPU	Register Select signal. RS=0: Command, RS=1: Data
5	R/W	MPU	Read/Write select signal, R/W=1: Read R/W: =0: Write
6	E	MPU	Operation Enable signal. Falling edge triggered.
7-10	DB0 – DB3	MPU	Four low order bi-directional three-state data bus lines. These four are not used during 4-bit operation.
11-14	DB4 – DB7	MPU	Four high order bi-directional three-state data bus lines.
15	LED+	Power Supply	Backlight Anode (+5.0V via on-board resistor)
16	LED-	Power Supply	Backlight Cathode (Ground)

Recommended LCD connector: 2.54mm pitch pins

Backlight connector: --- **Mates with:** ---



Electrical Characteristics

Item	Symbol	Condition	Min.	Typ.	Max.	Unit
Operating Temperature Range	T _{OP}	Absolute Max	-20	-	+70	°C
Storage Temperature Range	T _{ST}	Absolute Max	-30	-	+80	°C
Supply Voltage	V _{DD}	-	4.7	5.0	5.5	V
Supply Current	I _{DD}	V _{DD} =5.0V T _{OP} = 25°C	1.0	1.5	2.5	mA
Supply for LCD (contrast)	V _{LCD}		4.3	4.5	4.7	V
"H" Level input	V _{IH}	-	0.7*V _{DD}	-	V _{DD}	V
"L" Level input	V _{IL}	-	V _{SS}	-	0.6	V
"H" Level output	V _{OH}	-	3.9	-	V _{DD}	V
"L" Level output	V _{OL}	-	V _{SS}	-	0.4	V
Backlight Supply Voltage	V _{LED}	-	4.7	5.0	5.3	V
Backlight Supply Current	I _{LED}	V _{LED} =5.0V	5	7	15	mA

Optical Characteristics

Item		Symbol	Condition	Min.	Typ.	Max.	Unit
Optimal Viewing Angles	Top	φY+	CR ≥ 3	30	40	-	°
	Bottom	φY-		50	60	-	°
	Left	θX-		50	60	-	°
	Right	θX+		50	60	-	°
Contrast Ratio		CR	-	2	5	-	-
Response Time	Rise	T _R	T _{OP} = 25°C	-	150	250	ms
	Fall	T _F		-	200	300	ms

Controller Information

Built-in ST7066U controller.

Please download specification at http://www.newhavendisplay.com/app_notes/ST7066U.pdf

DDRAM Address

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
00	01	02	03	04	05	06	07	08	09	0A	0B	0C	0D	0E	0F
40	41	42	43	44	45	46	47	48	49	4A	4B	4C	4D	4E	4F

Table of Commands

Instruction	Instruction Code										Description	Description Time (270KHz)
	RS	R/W	DB7	DB6	DB5	DB4	DB3	DB2	DB1	DB0		
Clear Display	0	0	0	0	0	0	0	0	0	1	Write "20H" to DDRAM. and set DDRAM address to "00H" from AC	1.52 ms
Return Home	0	0	0	0	0	0	0	0	1	x	Set DDRAM address to "00H" from AC and return cursor to its original position if shifted. The contents of DDRAM are not changed.	1.52 ms
Entry Mode Set	0	0	0	0	0	0	0	1	I/D	S	Sets cursor move direction and specifies display shift. These operations are performed during data write and read.	37 us
Display ON/OFF	0	0	0	0	0	0	1	D	C	B	D=1:entire display on C=1:cursor on B=1:cursor position on	37 us
Cursor or Display Shift	0	0	0	0	0	1	S/C	R/L	x	x	Set cursor moving and display shift control bit, and the direction, without changing DDRAM data.	37 us
Function Set	0	0	0	0	1	DL	N	F	x	x	DL:interface data is 8/4 bits N:number of line is 2/1 F:font size is 5x11/5x8	37 us
Set CGRAM address	0	0	0	1	AC5	AC4	AC3	AC2	AC1	AC0	Set CGRAM address in address counter	37 us
Set DDRAM address	0	0	1	AC6	AC5	AC4	AC3	AC2	AC1	AC0	Set DDRAM address in address counter	37 us
Read Busy flag and address	0	1	BF	AC6	AC5	AC4	AC3	AC2	AC1	AC0	Whether during internal operation or not can be known by reading BF. The contents of address counter can also be read.	0 us
Write data to RAM	1	0	D7	D6	D5	D4	D3	D2	D1	D0	Write data into internal RAM (DDRAM/CGRAM)	37 us
Read data from RAM	1	1	D7	D6	D5	D4	D3	D2	D1	D0	Read data from internal RAM (DDRAM/CGRAM)	37 us

Built-in Font Table

Lower 4 Bits \ Upper 4 Bits		0000	0001	0010	0011	0100	0101	0110	0111	1000	1001	1010	1011	1100	1101	1110	1111
xxxx0000	CG RAM (1)			0	a	P	`	P					ー	ダ	ミ	α	ρ
xxxx0001	(2)			!	1	A	Q	a	q			。	ア	チ	△	ä	q
xxxx0010	(3)			"	2	B	R	b	r			「	イ	ツ	×	ß	θ
xxxx0011	(4)			#	3	C	S	c	s			」	ウ	テ	モ	ε	∞
xxxx0100	(5)			\$	4	D	T	d	t			、	エ	ト	パ	μ	Ω
xxxx0101	(6)			%	5	E	U	e	u			・	オ	ナ	ユ	ε	ü
xxxx0110	(7)			&	6	F	V	f	v			ヲ	カ	ニ	ヨ	ρ	Σ
xxxx0111	(8)			'	7	G	W	g	w			ア	キ	ヌ	ラ	g	π
xxxx1000	(1)			<	8	H	X	h	x			イ	ク	ネ	リ	、	⌘
xxxx1001	(2)			>	9	I	Y	i	y			ウ	ケ	ル	ル	´	y
xxxx1010	(3)			*	:	J	Z	j	z			エ	コ	ハ	レ	j	千
xxxx1011	(4)			+	;	K	[	k	<			オ	サ	ヒ	ロ	*	万
xxxx1100	(5)			,	<	L	¥	l	l			ヤ	シ	フ	ワ	¢	円
xxxx1101	(6)			—	=	M	]	m	}			ユ	ズ	ハ	ン	も	÷
xxxx1110	(7)			。	>	N	^	n	→			ヨ	セ	ホ	°	ñ	
xxxx1111	(8)			/	?	O	_	o	€			ッ	リ	マ	°	ö	■

Example Initialization Program

8-bit Initialization:

```

/*****/
void command(char i)
{
    P1 = i;                //put data on output Port
    D_I = 0;               //D/I=LOW : send instruction
    R_W = 0;               //R/W=LOW : Write
    E = 1;
    Delay(1);              //enable pulse width >= 300ns
    E = 0;                 //Clock enable: falling edge
}
/*****/
void write(char i)
{
    P1 = i;                //put data on output Port
    D_I = 1;               //D/I=HIGH : send data
    R_W = 0;               //R/W=LOW : Write
    E = 1;
    Delay(1);              //enable pulse width >= 300ns
    E = 0;                 //Clock enable: falling edge
}
/*****/
void init()
{
    E = 0;
    Delay(100);            //Wait >40 msec after power is applied
    command(0x30);          //command 0x30 = Wake up
    Delay(30);              //must wait 5ms, busy flag not available
    command(0x30);          //command 0x30 = Wake up #2
    Delay(10);              //must wait 160us, busy flag not available
    command(0x30);          //command 0x30 = Wake up #3
    Delay(10);              //must wait 160us, busy flag not available
    command(0x38);          //Function set: 8-bit/2-line
    command(0x10);          //Set cursor
    command(0x0c);          //Display ON; Cursor ON
    command(0x06);          //Entry mode set
}
/*****/
```

```

4-bit Initialization:
/*****/
void command(char i)
{
    P1 = i;                //put data on output Port
    D_I = 0;               //D/I=LOW : send instruction
    R_W = 0;               //R/W=LOW : Write
    Nybble();              //Send lower 4 bits
    i = i<<4;              //Shift over by 4 bits
    P1 = i;                //put data on output Port
    Nybble();              //Send upper 4 bits
}
/*****/
void write(char i)
{
    P1 = i;                //put data on output Port
    D_I = 1;               //D/I=HIGH : send data
    R_W = 0;               //R/W=LOW : Write
    Nybble();              //Clock lower 4 bits
    i = i<<4;              //Shift over by 4 bits
    P1 = i;                //put data on output Port
    Nybble();              //Clock upper 4 bits
}
/*****/
void Nybble()
{
    E = 1;
    Delay(1);              //enable pulse width >= 300ns
    E = 0;                 //Clock enable: falling edge
}
/*****/
void init()
{
    P1 = 0;
    P3 = 0;
    Delay(100);            //Wait >40 msec after power is applied
    P1 = 0x30;             //put 0x30 on the output port
    Delay(30);             //must wait 5ms, busy flag not available
    Nybble();              //command 0x30 = Wake up
    Delay(10);             //must wait 160us, busy flag not available
    Nybble();              //command 0x30 = Wake up #2
    Delay(10);             //must wait 160us, busy flag not available
    Nybble();              //command 0x30 = Wake up #3
    Delay(10);             //can check busy flag now instead of delay
    P1 = 0x20;             //put 0x20 on the output port
    Nybble();              //Function set: 4-bit interface
    command(0x28);         //Function set: 4-bit/2-line
    command(0x10);         //Set cursor
    command(0x0F);         //Display ON; Blinking cursor
    command(0x06);         //Entry Mode set
}
/*****/

```

Quality Information

Test Item	Content of Test	Test Condition	Note
High Temperature storage	Endurance test applying the high storage temperature for a long time.	+80°C , 48hrs	2
Low Temperature storage	Endurance test applying the low storage temperature for a long time.	-30°C , 48hrs	1,2
High Temperature Operation	Endurance test applying the electric stress (voltage & current) and the high thermal stress for a long time.	+70°C , 48hrs	2
Low Temperature Operation	Endurance test applying the electric stress (voltage & current) and the low thermal stress for a long time.	-20°C , 48hrs	1,2
High Temperature / Humidity Operation	Endurance test applying the electric stress (voltage & current) and the high thermal with high humidity stress for a long time.	+40°C , 90% RH , 48hrs	1,2
Thermal Shock resistance	Endurance test applying the electric stress (voltage & current) during a cycle of low and high thermal stress.	0°C, 30min -> 25°C, 5min -> 50°C, 30min = 1 cycle For 10 cycles	
Vibration test	Endurance test applying vibration to simulate transportation and use.	10-55Hz, 15mm amplitude. 60 sec in each of 3 directions X,Y,Z For 15 minutes	3
Static electricity test	Endurance test applying electric static discharge.	VS=800V, RS=1.5kΩ, CS=100pF One time	

Note 1: No condensation to be observed.

Note 2: Conducted after 4 hours of storage at 25°C, 0%RH.

Note 3: Test performed on product itself, not inside a container.

Precautions for using LCDs/LCMs

See Precautions at www.newhavendisplay.com/specs/precautions.pdf

Warranty Information and Terms & Conditions

http://www.newhavendisplay.com/index.php?main_page=terms